

Strong normalization in the simply-typed system of the ρ -cube

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joint work with C. Kirchner, L. Liquori, H. Cirstea

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Untyped translation

Dealing with types

Strong normalization

What's next

Encoding the ρ -calculus in λ -calculus

$$\llbracket X \rrbracket \triangleq X$$

$$\llbracket f_i \rrbracket \triangleq \lambda x_1 \dots \lambda x_{\alpha_i}. (\lambda z_1 \dots \lambda z_S. (z_i x_1 \dots x_{\alpha_i}))$$

$$\llbracket f_i \bullet B_1 \dots \bullet B_{\alpha_i} \rrbracket \triangleq \lambda z_1 \dots \lambda z_S. (z_i B_1 \dots B_{\alpha_i})$$

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$$\llbracket (f_i \bullet X_1 \bullet \dots \bullet X_p) \rightarrow A \rrbracket \triangleq \lambda y. (y \underbrace{x_\perp \dots x_\perp}_{(\alpha_i - p)} \underbrace{x_\perp \dots x_\perp}_{(i-1)} \lambda X_1 \dots \lambda X_p. \llbracket A \rrbracket \underbrace{x_\perp \dots x_\perp}_{(S-i)})$$

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$$\llbracket X \rightarrow A \rrbracket \triangleq \lambda X. \llbracket A \rrbracket$$

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$$\llbracket X \rightarrow A \rrbracket \triangleq \lambda X. \llbracket A \rrbracket$$

$$\llbracket A \bullet B \rrbracket \triangleq \llbracket A \rrbracket \llbracket B \rrbracket$$

$$\llbracket A; B \rrbracket \triangleq \lambda x_1 \dots \lambda x_\alpha. \left((\lambda z. (\llbracket A \rrbracket x_1 \dots x_\alpha)) (\llbracket B \rrbracket x_1 \dots x_\alpha) \right)$$

Examples

$$(Success) \quad \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f \bullet X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_1 Y)}_{\llbracket f \bullet Y \rrbracket}$$

Examples

$$\begin{array}{l}
 (\text{Success}) \\
 \vdash_{\beta} \underbrace{(\lambda y. (y (\lambda X. X) x_{\perp}))}_{\llbracket f^{\bullet} X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2. (z_1 Y)}_{\llbracket f^{\bullet} Y \rrbracket} \\
 \underbrace{(\lambda z_1 \lambda z_2. (z_1 Y)) (\lambda X. X) x_{\perp}}_{\llbracket [f^{\bullet} X \ll f^{\bullet} Y] X \rrbracket}
 \end{array}$$

Examples

(*Success*)

$$\begin{aligned}
 & \underbrace{(\lambda y. (y (\lambda X. X) x_{\perp}))}_{\llbracket f^{\bullet} X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2. (z_1 Y)}_{\llbracket f^{\bullet} Y \rrbracket} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2. (z_1 Y)) (\lambda X. X) x_{\perp}}_{\llbracket [f^{\bullet} X \ll f^{\bullet} Y] X \rrbracket} \\
 \mapsto_{\beta} & (\lambda z_2. ((\lambda X. X) Y)) x_{\perp}
 \end{aligned}$$

Examples

(*Success*)

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 & \underbrace{(\lambda y. (y (\lambda X. X) x_{\perp}))}_{\llbracket f^{\bullet} X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2. (z_1 Y)}_{\llbracket f^{\bullet} Y \rrbracket} \\
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 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f \bullet X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_1 Y)}_{\llbracket f \bullet Y \rrbracket} \\
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 \mapsto_{\beta} & (\lambda z_2.((\lambda X.X)Y))x_{\perp} \\
 \mapsto_{\beta} & (\lambda X.X)Y \\
 \mapsto_{\beta} & Y
 \end{aligned}$$

(*Failure*)

$$\underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f \bullet X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_2 Y)}_{\llbracket g \bullet Y \rrbracket}$$

Examples

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$$\begin{aligned}
 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f^{\bullet}X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_1 Y)}_{\llbracket f^{\bullet}Y \rrbracket} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2.(z_1 Y))}_{\llbracket [f^{\bullet}X \ll f^{\bullet}Y] X \rrbracket} (\lambda X.X)x_{\perp} \\
 \mapsto_{\beta} & (\lambda z_2.((\lambda X.X)Y))x_{\perp} \\
 \mapsto_{\beta} & (\lambda X.X)Y \\
 \mapsto_{\beta} & Y
 \end{aligned}$$

(*Failure*)

$$\begin{aligned}
 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f^{\bullet}X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_2 Y)}_{\llbracket g^{\bullet}Y \rrbracket} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2.(z_2 Y))}_{\llbracket [f^{\bullet}X \ll g^{\bullet}Y] X \rrbracket} (\lambda X.X)x_{\perp}
 \end{aligned}$$

Examples

(*Success*)

$$\begin{aligned}
 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{[[f^{\bullet}X \rightarrow X]]} \underbrace{\lambda z_1 \lambda z_2.(z_1 Y)}_{[[f^{\bullet}Y]]} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2.(z_1 Y))}_{[[[f^{\bullet}X \ll f^{\bullet}Y]X]]} (\lambda X.X)x_{\perp} \\
 \mapsto_{\beta} & (\lambda z_2.((\lambda X.X)Y))x_{\perp} \\
 \mapsto_{\beta} & (\lambda X.X)Y \\
 \mapsto_{\beta} & Y
 \end{aligned}$$

(*Failure*)

$$\begin{aligned}
 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{[[f^{\bullet}X \rightarrow X]]} \underbrace{\lambda z_1 \lambda z_2.(z_2 Y)}_{[[g^{\bullet}Y]]} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2.(z_2 Y))}_{[[[f^{\bullet}X \ll g^{\bullet}Y]X]]} (\lambda X.X)x_{\perp} \\
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 \mapsto_{\beta} & (\lambda z_2.((\lambda X.X)Y))x_{\perp} \\
 \mapsto_{\beta} & (\lambda X.X)Y \\
 \mapsto_{\beta} & Y
 \end{aligned}$$

(*Failure*)

$$\begin{aligned}
 & \underbrace{(\lambda y.(y(\lambda X.X)x_{\perp}))}_{\llbracket f^{\bullet}X \rightarrow X \rrbracket} \underbrace{\lambda z_1 \lambda z_2.(z_2 Y)}_{\llbracket g^{\bullet}Y \rrbracket} \\
 \mapsto_{\beta} & \underbrace{(\lambda z_1 \lambda z_2.(z_2 Y))}_{\llbracket [f^{\bullet}X \ll g^{\bullet}Y]X \rrbracket} (\lambda X.X)x_{\perp} \\
 \mapsto_{\beta} & (\lambda z_2.(z_2 Y))x_{\perp} \\
 \mapsto_{\beta} & x_{\perp}Y
 \end{aligned}$$

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Constants

Variables

Constraints

The type of a constant

$$\begin{array}{c}
 \frac{\Gamma \vdash z_i : \sigma_1 \rightarrow \sigma_2 \rightarrow \beta \quad (\forall n \in [1, 2]) \Gamma \vdash x_n : \sigma_n}{\Gamma \vdash z_i x_1 x_2 : \beta} \text{ (APP)} \\
 \frac{}{x_{\perp} : \beta, \overrightarrow{x_n : \sigma_n} \vdash \lambda z_1 \dots \lambda z_S. (z_i x_1 x_2) : [\sigma_1 \rightarrow \sigma_2 \rightarrow \beta]^S \rightarrow \beta} \text{ (ABS)} \\
 \frac{}{x_{\perp} : \beta \vdash \llbracket f_i \rrbracket = \lambda x_1. \lambda x_2. \lambda z_1 \dots \lambda z_S. (z_i x_1 x_2) : \sigma_1 \rightarrow \sigma_2 \rightarrow [\sigma_1 \rightarrow \sigma_2 \rightarrow \beta]^S \rightarrow \beta} \text{ (ABS)}
 \end{array}$$

where $[\sigma]^S \rightarrow \tau \triangleq \underbrace{\sigma \rightarrow \dots \rightarrow \sigma}_S \rightarrow \tau$

$$\vdash \llbracket f_i(B_1, B_2) \rrbracket : [\sigma_1 \rightarrow \sigma_2 \rightarrow \beta]^S \rightarrow \beta$$

Type of $\llbracket f_i(X_1, X_2) \rightarrow A \rrbracket$

$$\begin{array}{c}
 \frac{X_1 : \sigma_1, X_2 : \sigma_2 \vdash \llbracket A \rrbracket : \tau}{\vdash \lambda X_1. \lambda X_2. \llbracket A \rrbracket : \sigma_1 \rightarrow \sigma_2 \rightarrow \tau} \text{ (ABS)} \\
 \frac{\vdash x_{\perp} : \sigma_1 \rightarrow \sigma_2 \rightarrow \tau \quad \vdash \lambda X_1. \lambda X_2. \llbracket A \rrbracket : \sigma_1 \rightarrow \sigma_2 \rightarrow \tau}{\vdash y \vec{x}_{\perp} (\lambda X_1. \lambda X_2. \llbracket A \rrbracket) \vec{x}_{\perp} : \gamma} \text{ (APP)} \\
 \frac{\vdash y \vec{x}_{\perp} (\lambda X_1. \lambda X_2. \llbracket A \rrbracket) \vec{x}_{\perp} : \gamma}{\vdash \lambda y. (y \vec{x}_{\perp} (\lambda X_1. \lambda X_2. \llbracket A \rrbracket) \vec{x}_{\perp}) : \left([\sigma_1 \rightarrow \sigma_2 \rightarrow \tau]^S \rightarrow \gamma \right) \rightarrow \gamma} \text{ (ABS)}
 \end{array}$$

$$[\sigma_1 \rightarrow \sigma_2 \rightarrow \tau]^S \rightarrow \gamma = [\sigma_1 \rightarrow \sigma_2 \rightarrow \beta]^S \rightarrow \beta \text{ thus } \tau = \beta = \gamma$$

$$\begin{aligned}
 \{\sigma_1, \dots, \sigma_{\alpha}\} &\triangleq \Pi(\beta : *) . ([\sigma_1 \rightarrow \dots \sigma_{\alpha} \rightarrow \beta]^S \rightarrow \beta) \\
 \{\emptyset\} &\triangleq \Pi(\beta : *) . ([\beta]^S \rightarrow \beta)
 \end{aligned}$$

Enhanced translation

$$\vdash x_{\perp} \quad : \quad \perp$$

$$\begin{aligned} \llbracket f_i \rrbracket &\stackrel{\triangle}{=} \lambda x_1. \lambda x_2. \lambda(\beta : *) (\lambda z_1 \dots \lambda z_S. (z_i x_1 x_2)) \\ &: \sigma_1 \rightarrow \sigma_2 \rightarrow \{\sigma_1, \sigma_2\} \end{aligned}$$

$$\begin{aligned} \llbracket f_i(X_1, X_2) \rightarrow_{\Delta} A \rrbracket &\stackrel{\triangle}{=} \lambda y. (y \ \tau \ \overrightarrow{(x_{\perp} \tau_0)} \ \lambda X_1. \lambda X_2. \llbracket A \rrbracket \ \overrightarrow{(x_{\perp} \tau_0)}) \\ &: \{\sigma_1, \sigma_2\} \rightarrow \tau \end{aligned}$$

where $\llbracket \Gamma \rrbracket \vdash_{F\omega} \llbracket A \rrbracket : \tau$

and $\llbracket \Gamma \rrbracket \vdash_{F\omega} \lambda X_1. \lambda X_2. \llbracket A \rrbracket : \tau_0$

Constants

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The type of a variable

$$(\Xi : *), (X : Y \rightarrow_{Y:\Xi} \Xi) \vdash_{\rho} X : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *) \vdash_{\rho} Y \rightarrow_{Y:\Xi} Y : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *), (a : \Xi) \vdash_{\rho} Y \rightarrow_{Y:\Xi} a : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *), (f : Y \rightarrow_{Y:\Xi} \Xi) \vdash_{\rho} f : Y \rightarrow_{Y:\Xi} \Xi$$

The type of a variable

$$(\Xi : *), (X : Y \rightarrow_{Y:\Xi} \Xi) \vdash_{\rho} X \quad : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *) \vdash_{\rho} Y \rightarrow_{Y:\Xi} Y \quad : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *), (a : \Xi) \vdash_{\rho} Y \rightarrow_{Y:\Xi} a \quad : Y \rightarrow_{Y:\Xi} \Xi$$

$$(\Xi : *), (f : Y \rightarrow_{Y:\Xi} \Xi) \vdash_{\rho} f \quad : Y \rightarrow_{Y:\Xi} \Xi$$

$$\Gamma \vdash_{F\omega} \lambda(\beta_Y : *). \lambda(Y : \beta_Y). Y \quad : \Pi(\beta_Y : *). (\beta_Y \rightarrow \beta_Y)$$

$$\Gamma \vdash_{F\omega} \lambda(\beta_Y : *). \lambda(Y : \beta_Y). \llbracket a \rrbracket \quad : \Pi(\beta_Y : *). (\beta_Y \rightarrow \{\emptyset\})$$

$$\Gamma \vdash_{F\omega} \llbracket f \rrbracket \quad : \Pi(\beta_Y : *). (\beta_Y \rightarrow \{\beta_Y\})$$

Use of types depending on types

$$\llbracket Y \rightarrow_{Y:\Xi} \Xi \rrbracket^X = \Pi(\beta_Y : *).(\beta_Y \rightarrow \beta_X \beta_Y)$$

with $\beta_X : * \rightarrow *$

$Y \rightarrow Y$	$\Pi(\beta_Y : *). \beta_Y \rightarrow \beta_Y$	$\beta_X := \lambda(\beta : *). \beta$
$Y \rightarrow a$	$\Pi(\beta_Y : *). \beta_Y \rightarrow \{\emptyset\}$	$\beta_X := \lambda(\beta : *). \{\emptyset\}$
f	$\Pi(\beta_Y : *). \beta_Y \rightarrow \{\beta_Y\}$	$\beta_X := \lambda(\beta : *). \{\beta\}$

Generalization for arbitrary types and contexts

$$\mathbb{K}(Y_1 \rightarrow_{Y_1:\Phi_1} \dots Y_n \rightarrow_{Y_n:\Phi_n} \Xi) \triangleq \text{a suitable kind for } \beta_X$$

$$\begin{aligned} \llbracket Y_1 \rightarrow_{Y_1:\Phi_1} \dots Y_n \rightarrow_{Y_n:\Phi_n} \Xi \rrbracket^X &\triangleq \Pi \beta_{Y_1} : \mathbb{K}(\Phi_{Y_1}). (\llbracket \Phi_{Y_1} \rrbracket^{Y_1} \rightarrow \dots \\ &\quad \Pi \beta_{Y_n} : \mathbb{K}(\Phi_{Y_n}). (\llbracket \Phi_{Y_n} \rrbracket^{Y_n} \rightarrow \beta_X \overrightarrow{\beta_{Y_i}})) \end{aligned}$$

$$\llbracket \emptyset \rrbracket \triangleq x_{\perp} : \perp$$

$$\llbracket \Gamma, X : \Phi \rrbracket \triangleq \llbracket \Gamma \rrbracket, \beta_X : \mathbb{K}(\Phi)_{\emptyset}, X : \llbracket \Phi \rrbracket_{\emptyset}^X$$

Constants
Variables
Constraints

The type of an application

Suppose $\Sigma, \Gamma \vdash_{\rho} A \bullet B : [f(X_1 \dots X_n) \ll_{\Delta} B] \Psi$

and $[[\Gamma]] \vdash_{F\omega} [[B]] : \sigma$

$$[[A \bullet B]] \triangleq [[A]] \tau_{X_1} \dots \tau_{X_n} [[B]]$$

if $\sigma =_{\beta} \{[[\Phi_1]]^{X_1} \dots [[\Phi_n]]^{X_n}\} [\beta_{X_1} := \tau_{X_1} \dots \beta_X := \tau_X]$

$$[[A \bullet B]] \triangleq \lambda \overrightarrow{\beta'_X : \mathbb{K}(\Phi_X)}. \lambda \left(w : \sigma \rightarrow \{[[\Phi_1]]^{X'_1} \dots [[\Phi_n]]^{X'_n}\} \right). \left([[A]] \overrightarrow{\beta'_X} (w [[B]]) \right)$$

if $\nexists \overrightarrow{\tau_X}, \sigma =_{\beta} \{[[\Phi_1]]^{X_1} \dots [[\Phi_n]]^{X_n}\} [\overrightarrow{\beta_X := \tau_X}]$

Constraint resolution

$$\llbracket A \bullet B \rrbracket \triangleq \overrightarrow{\lambda \beta'_X : \mathbb{K}(\Phi_X)}. \lambda \left(w : \sigma \rightarrow \left\{ \llbracket \Phi_1 \rrbracket^{X'_1} \dots \llbracket \Phi_n \rrbracket^{X'_n} \right\} \right). \left(\llbracket A \rrbracket \overrightarrow{\beta'_X} (w \llbracket B \rrbracket) \right)$$

If a subsequent instantiation θ_0 of some free type variables (in σ) enforces:

$$\exists \overrightarrow{\tau_X}, \sigma \theta_0 \quad \stackrel{\beta}{=} \left\{ \llbracket \Phi_1 \rrbracket^{X'_1} \dots \llbracket \Phi_n \rrbracket^{X'_n} \right\} \overrightarrow{[\beta_X := \tau_X]}$$

Constraint resolution

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- In the term, using an enhanced η -expansion, $w := \lambda x.x$

Before the constraint is resolved in the types, there can be no σ -reduction...

Constraint resolution

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If a subsequent instantiation θ_0 of some free type variables (in σ) enforces:

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- In the term, using an enhanced η -expansion, $w := \lambda x.x$

Before the constraint is resolved in the types, there can be no σ -reduction...

- In the types, nothing to be done !

$$\vdash_{F\omega} w : \sigma \theta_0 \rightarrow \left\{ \llbracket \Phi_1 \rrbracket^{X'_1} \dots \llbracket \Phi_n \rrbracket^{X'_n} \right\} \overrightarrow{[\beta_X := \tau_X]}$$

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Steps of the proof

- Faithful reductions
- Typability of the translated terms
- Strong normalization

Steps of the proof

- Faithful reductions

If $A \mapsto_{\rho\omega} B$, then $\llbracket A \rrbracket \xrightarrow{\beta} \llbracket B \rrbracket$ in at least one step.

- Typability of the translated terms

- Strong normalization

Steps of the proof

- Faithful reductions

If $A \mapsto_{\rho\delta} B$, then $\llbracket A \rrbracket \xrightarrow{\beta} \llbracket B \rrbracket$ in at least one step.

- Typability of the translated terms

Giving a fresh variable Z ,

$$\Sigma, \Gamma \vdash_{\rho} A : \Phi \quad \Rightarrow \quad \exists \tau_A, \quad \llbracket \Gamma \rrbracket \vdash_{F\omega} \llbracket A \rrbracket : \llbracket \Phi \rrbracket_{\emptyset}^Z [\beta_Z := \tau_A]$$

- Strong normalization

Steps of the proof

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If $A \mapsto_{\rho\delta} B$, then $\llbracket A \rrbracket \xrightarrow{\beta} \llbracket B \rrbracket$ in at least one step.

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Giving a fresh variable Z ,

$$\Sigma, \Gamma \vdash_{\rho} A : \Phi \quad \Rightarrow \quad \exists \tau_A, \quad \llbracket \Gamma \rrbracket \vdash_{F\omega} \llbracket A \rrbracket : \llbracket \Phi \rrbracket_{\emptyset}^Z [\beta_Z := \tau_A]$$

- Strong normalization

If $\Sigma, \Gamma \vdash_{\rho} A : \Phi$ then A and Φ are strongly normalizing.

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What's next

Towards an extension of Curry-Howard

- Some open questions

⇒ What do the types $A \rightarrow C$ and $[A \ll B].C$ mean ?

⇒ Are the structures suitable for products or sums ?

Towards an extension of Curry-Howard

- Some open questions

- ⇒ What do the types $A \rightarrow C$ and $[A \ll B].C$ mean ?

- ⇒ Are the structures suitable for products or sums ?

- Some partial answers

- ⇒ The λ -term $[[f(X_1 \dots X_n)]]$ has type $\bigwedge_{i=1..n} X_i$.

- ⇒ Proof assistant based on the ρ -calculus: deduction and computation at the same level.

- ⇒ Use of the typed fixpoints to model trustworthy computations steps.

Example with a delayed constraint

$$(Y \rightarrow (f \bullet X \rightarrow X) \bullet Y) \bullet (f \bullet a)$$

Example with a delayed constraint

$$\begin{aligned} & (Y \rightarrow (f \bullet X \rightarrow X) \bullet Y) \bullet (f \bullet a) \\ \mapsto_{\rho} & (Y \rightarrow [f \bullet X \ll Y] X) \bullet (f \bullet a) \end{aligned}$$

Example with a delayed constraint

$$\begin{aligned} & (Y \rightarrow (f \bullet X \rightarrow X) \bullet Y) \bullet (f \bullet a) \\ \mapsto_{\rho} & (Y \rightarrow [f \bullet X \ll Y] X) \bullet (f \bullet a) \\ \mapsto_{\rho} & [Y \ll f \bullet a] [f \bullet X \ll Y] X \end{aligned}$$

Example with a delayed constraint

$$\begin{aligned} & (Y \rightarrow (f \bullet X \rightarrow X) \bullet Y) \bullet (f \bullet a) \\ \mapsto_{\rho} & (Y \rightarrow [f \bullet X \ll Y] X) \bullet (f \bullet a) \\ \mapsto_{\rho} & [Y \ll f \bullet a] [f \bullet X \ll Y] X \\ \mapsto_{\sigma} & [f \bullet X \ll f \bullet a] X \end{aligned}$$

Example with a delayed constraint

$$(Y \rightarrow (f \bullet X \rightarrow X) \bullet Y) \bullet (f \bullet a)$$

$$\vdash_{\rho} (Y \rightarrow [f \bullet X \ll Y] X) \bullet (f \bullet a)$$

$$\vdash_{\rho} [Y \ll f \bullet a] [f \bullet X \ll Y] X$$

$$\vdash_{\sigma} [f \bullet X \ll f \bullet a] X$$

$$\vdash_{\sigma} a$$

Example with a delayed constraint (cont'd)

$$(\lambda Y. \underbrace{(\lambda y. (yx_{\perp} (\lambda X. X)))}_{\llbracket f \bullet X \rightarrow X \rrbracket} Y) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right)$$

Example with a delayed constraint (cont'd)

$$\begin{array}{l}
 (\lambda Y. \left(\underbrace{(\lambda y. (yx \perp (\lambda X. X)))}_{\llbracket f \bullet X \rightarrow X \rrbracket} Y \right)) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right) \\
 \mapsto_{\beta} \underbrace{(\lambda Y. (Y x \perp (\lambda X. X)))}_{\llbracket Y \rightarrow [f \bullet X \ll Y] X \rrbracket} \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right)
 \end{array}$$

Example with a delayed constraint (cont'd)

$$\begin{aligned}
 & (\lambda Y. \left(\underbrace{(\lambda y. (yx \perp (\lambda X. X)))}_{[[f \bullet X \rightarrow X]]} Y \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x \perp (\lambda X. X)) \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & (\lambda Y. (Y x \perp (\lambda X. X))) \left(\lambda z_1 \lambda z_2. (z_2 \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]])} \right)
 \end{aligned}$$

Example with a delayed constraint (cont'd)

$$\begin{aligned}
 & (\lambda Y. \left(\underbrace{(\lambda y. (yx_{\perp} (\lambda X. X)))}_{\llbracket f \bullet X \rightarrow X \rrbracket} Y \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right) \\
 \mapsto_{\beta} & \left(\underbrace{\lambda Y. (Y x_{\perp} (\lambda X. X))}_{\llbracket Y \rightarrow [f \bullet X \ll Y] X \rrbracket} \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right) \\
 \mapsto_{\beta} & (\lambda Y. (Y x_{\perp} (\lambda X. X))) \left(\lambda z_1 \lambda z_2. (z_2 \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket}) \right) \\
 \mapsto_{\beta} & (\lambda z_1 \lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) x_{\perp} (\lambda X. X) \quad (f \neq a)
 \end{aligned}$$

Example with a delayed constraint (cont'd)

$$\begin{aligned}
 & (\lambda Y. \left(\underbrace{(\lambda y. (yx_{\perp} (\lambda X. X)))}_{\llbracket f \bullet X \rightarrow X \rrbracket} Y \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x_{\perp} (\lambda X. X)) \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{\llbracket f \rrbracket} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x_{\perp} (\lambda X. X)) \right) (\lambda z_1 \lambda z_2. (z_2 \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{\llbracket a \rrbracket})) \\
 \mapsto_{\beta} & (\lambda z_1 \lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) x_{\perp} (\lambda X. X) \quad (f \neq a) \\
 \mapsto_{\beta} & (\lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) (\lambda X. X) \quad (f = f)
 \end{aligned}$$

Example with a delayed constraint (cont'd)

$$\begin{aligned}
 & (\lambda Y. \left(\underbrace{(\lambda y. (yx_{\perp} (\lambda X. X)))}_{[[f \bullet X \rightarrow X]]} Y \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x_{\perp} (\lambda X. X)) \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x_{\perp} (\lambda X. X)) \right) (\lambda z_1 \lambda z_2. (z_2 \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]})) \\
 \mapsto_{\beta} & (\lambda z_1 \lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) x_{\perp} (\lambda X. X) \quad (f \neq a) \\
 \mapsto_{\beta} & (\lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) (\lambda X. X) \quad (f = f) \\
 \mapsto_{\beta} & (\lambda X. X) (\lambda u_1 \lambda u_2. u_1)
 \end{aligned}$$

Example with a delayed constraint (cont'd)

$$\begin{aligned}
 & (\lambda Y. \left(\underbrace{(\lambda y. (yx_{\perp} (\lambda X. X)))}_{[[f \bullet X \rightarrow X]]} Y \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & \left(\lambda Y. (Y x_{\perp} (\lambda X. X)) \right) \left(\underbrace{(\lambda x_1. \lambda z_1 \lambda z_2. (z_2 x_1))}_{[[f]]} \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]]} \right) \\
 \mapsto_{\beta} & (\lambda Y. (Y x_{\perp} (\lambda X. X))) \left(\lambda z_1 \lambda z_2. (z_2 \underbrace{(\lambda u_1 \lambda u_2. u_1)}_{[[a]])} \right) \\
 \mapsto_{\beta} & (\lambda z_1 \lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) x_{\perp} (\lambda X. X) \quad (f \neq a) \\
 \mapsto_{\beta} & (\lambda z_2. (z_2 (\lambda u_1 \lambda u_2. u_1))) (\lambda X. X) \quad (f = f) \\
 \mapsto_{\beta} & (\lambda X. X) (\lambda u_1 \lambda u_2. u_1) \\
 \mapsto_{\beta} & (\lambda u_1 \lambda u_2. u_1) \\
 = & \quad [[a]]
 \end{aligned}$$